

1.

(a) Rewrite A as follows:
$$A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \\ 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \\ 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 6 & 2 \end{bmatrix} = QB,$$

where Q has orthonormal columns, implying $Q^T Q = I$. The normal equation $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$ satisfied by the least-squares solution $\hat{\mathbf{x}}$ becomes

$$\begin{aligned} (QB)^T (QB) \hat{\mathbf{x}} &= (QB)^T \mathbf{b} \\ \Rightarrow B^T Q^T QB \hat{\mathbf{x}} &= B^T Q^T \mathbf{b} \\ \Rightarrow Q^T QB \hat{\mathbf{x}} &= Q^T \mathbf{b} \\ \Rightarrow B \hat{\mathbf{x}} &= Q^T \mathbf{b} \end{aligned}$$

That is, $\begin{bmatrix} 2 & 0 \\ 6 & 2 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$. Solving yields $\begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 1/4 \\ -1/2 \end{bmatrix}$.

- (b) Let P be the orthogonal projection matrix onto the column space of A . Since $C(A) = C(Q)$, P is the orthogonal projection matrix onto the column space of Q . Because Q has orthonormal columns, it follows that

$$P = QQ^T = \frac{1}{2} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}. \text{ Since the closest vector in } C(A) \text{ to } \mathbf{z} \text{ is the}$$

orthogonal projection of \mathbf{z} onto $C(A)$, our goal is to solve $P\mathbf{z} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$. The

general solution is given by $\mathbf{z} = \begin{bmatrix} 2 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \alpha \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \beta \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$.

- (c) The nullspace of A^T is the orthogonal complement of the column space of A . Therefore, the orthogonal projection matrix onto $N(A^T)$ is

$$I - P = \frac{1}{2} \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}.$$

- (d) True. Because $N(A^T) = N(AA^T)$, M is also the orthogonal projection matrix onto the nullspace of A^T . Since the column space of A is the orthogonal complement of $N(A^T)$, the orthogonal projection of every column of A onto $N(AA^T)$ must be zero. Therefore, $MA = 0$.

2.

- (a) The standard matrix of T is $A = \begin{bmatrix} 4 & -2 \\ -5 & 3 \end{bmatrix}$. The area of $T(S)$ is the

product of the area of S and $|\det A|$. The area of S is 2 and $|\det A| = 2$.

Thus, the area of $T(S)$ is 4.

- (b) Let $B = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$. Note that $\mathbf{x} = B[\mathbf{x}]_\beta$ and $[T(\mathbf{x})]_\beta = A[\mathbf{x}]_\beta$. It follows

that $T(\mathbf{x}) = B[T(\mathbf{x})]_\beta = BA[\mathbf{x}]_\beta = BAB^{-1}\mathbf{x}$. Hence,

$$T(2, 5) = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 2 \\ 5 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}.$$

- (c) True. Because $\{p(t), q(t), r(t)\}$ is linearly independent,

$c_1p(t) + c_2q(t) + c_3r(t) = 0$ implies $c_1 = c_2 = c_3 = 0$. Thus,

$$\begin{aligned} & d_1(p(t) + q(t)) + d_2(q(t) + r(t)) + d_3(p(t) + r(t)) \\ &= (d_1 + d_3)p(t) + (d_1 + d_2)q(t) + (d_2 + d_3)r(t) = 0 \end{aligned}$$

implies $d_1 + d_3 = d_1 + d_2 = d_2 + d_3 = 0$. Solving yields $d_1 = d_2 = d_3 = 0$.

This proves that $\{p(t) + q(t), q(t) + r(t), p(t) + r(t)\}$ is linearly independent.

- (d) Since A is 6 by 3 and is one-to-one, $\dim C(A) = 3 - \dim N(A) = 3 - 0 = 3$. Because B maps \mathbb{R}^5 onto \mathbb{R}^3 , the range (column space) of B is \mathbb{R}^3 . This means that $C(AB) = C(A)$. Therefore, $\text{rank}(AB) = \dim C(AB) = \dim C(A) = 3$.

3.

$$(a) \begin{vmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 4 & 2 & 3 \\ 0 & 0 & 5 & 3 & 5 \\ 5 & 3 & 9 & 8 & 4 \\ 8 & 5 & 4 & 6 & 3 \end{vmatrix} = - \begin{vmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 4 & 2 & 3 & 0 \\ 0 & 5 & 3 & 5 & 0 \\ 5 & 9 & 8 & 4 & 3 \\ 8 & 4 & 6 & 3 & 5 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 & 0 & 0 \\ 4 & 2 & 3 & 0 & 0 \\ 5 & 3 & 5 & 0 & 0 \\ 5 & 8 & 4 & 5 & 3 \\ 8 & 6 & 3 & 8 & 5 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ 4 & 2 & 3 \\ 5 & 3 & 5 \end{vmatrix} \begin{vmatrix} 5 & 3 \\ 8 & 5 \end{vmatrix} = 1 \cdot 1 = 1$$

(b) If all entries of A and A^{-1} are integers, then $\det A$ and $\det A^{-1}$ are nonzero integers. However, $\det A^{-1} = \frac{1}{\det A}$. So we must have $\det A = 1$ or -1 .

(c) Recall that $AC^T = (\det A)I_n$. Taking determinant,

$$\det(AC^T) = (\det A)(\det C^T) = (\det A)^n (\det I_n) = (\det A)^n. \text{ We obtain}$$

$\det C = \det C^T = (\det A)^{n-1}$. If A is singular, it follows that $\det A = 0$, and thus $\det C = 0$. Therefore, C is singular.